

Composing knowledge graphs, inside and out

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About me (Spencer Breiner)

National Institute of Standards and Technology

- Information Technology Lab - Software & Systems Division
- Ph.D., CMU, 2013 - Category theory (CT) and logic

Current work: *Applied* CT for systems modeling

- Knowledge representation
- Knowledge integration
- Multiple semantics

Outline for today:

- Graphs & categories
- Why not (just) graphs?
- Knowledge graphs as categories and functors

What's beneath a knowledge graph?

Knowledge Graphs:

*“structured representations of semantic
knowledge that are stored in a graph”*

What structure? Stored how?

Today, some possible answers from category theory.

Some themes:

Bite-size ontologies

Data/concept duality

Internalized computation/proof

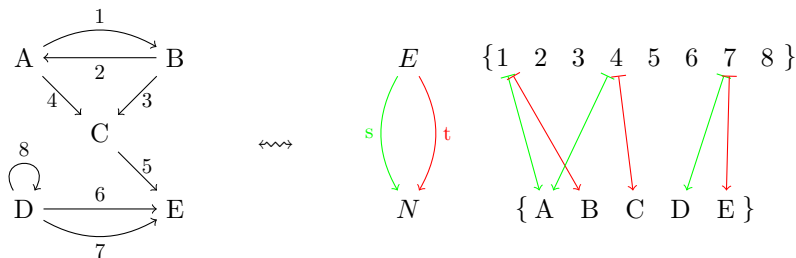
Graphs

For today, graphs are *directed* and (optionally) *multi*-.

Any graph can be represented as

- A pair of sets $N = \text{Node}$ and $E = \text{Edge}$, and
- A pair of functions $s = \text{src}, t = \text{tgt} : E \Rightarrow N$.

For example,



Categories

A category is a graph G together with

- Version 1: A partial associative operation (with identities)

$$\begin{array}{c} E \times E \\ \cup \\ \{f.\mathbf{tgt} = g.\mathbf{src}\} \end{array} \xrightarrow{f.g} E$$

Semantic categories: **Sets**, **Graph**, **Vect**, **Type**

- Version 2: A (concat-stable) equivalence relation over paths

$$\{\langle f_i \rangle \sim \langle g_j \rangle\} \subseteq \mathbf{Path}(G) \times \mathbf{Path}(G)$$

Schemas: $\mathcal{G} = \langle E \rightrightarrows N \rangle$, $\mathcal{P} = \mathbf{OSProb}$, $\mathcal{S} = \mathbf{OSSoln}$

Free categories (!)

Upshot: Any graph G already “is” a category.

The relationship is mediated by a free/forgetful *adjunction*

$$\begin{array}{ccc} & \mathbf{Cat} & \\ \text{Free} \swarrow & & \searrow \text{Forget} \\ & \mathbf{Graph} & \end{array} \quad \frac{\mathbf{Free}(G) \longrightarrow \mathbf{C} \quad \in \mathbf{Cat}}{G \longrightarrow \mathbf{Forget}(\mathbf{C}) \quad \in \mathbf{Graph}}$$

Two round trips:

A *monad* $\eta_G : G \rightarrow \mathbf{Path}(G)$ (concat)

A *comonad* $\epsilon_C : \mathbf{Factor}(\mathbf{C}) \rightarrow \mathbf{C}$ (compute)

A bite-sized example

Open-shop scheduling

Problem					
Jobs		j_1	j_2	j_3	j_4
Machines	saw	2 hr	2 hr	2 hr	1 hr
	drill	2 hr	3 hr	0	3 hr
	lathe	2 hr	3 hr	3 hr	0
	mill	2 hr	2 hr	1 hr	3 hr

Schedule										
	1	2	3	4	5	6	7	8	9	10
saw	j_1			j_4		j_2			j_3	
drill		j_2		j_1				j_4		
lathe		j_3				j_1			j_2	
mill		j_4		j_2	j_3			j_1		

Schematically,

$$\mathcal{P} = \langle \tau : J \times M \longrightarrow \mathbb{R}^+ \rangle$$

$$\mathcal{S} = \langle s, t : J \times M \rightrightarrows \mathbb{R}^+ \mid \text{ax.} \rangle$$

The two are related via a functor

$$\begin{array}{ccc} F : \mathcal{P} & \longrightarrow & \mathcal{S} \\ \tau & \longmapsto & t - s \end{array}$$

Functorial semantics & duality

$F : \mathcal{P} \rightarrow \mathcal{S}$ encodes: “every schedule solves *some* problem.”

Any concrete schedule (instance) defines a functor $P : \mathcal{P} \rightarrow \mathbf{Sets}$

Nodes map to sets: $P(J) = \{j_1, j_2, j_3, j_4\}$

Edges map to functions: $P(\tau) : (j_2, \text{lathe}) \mapsto 3 \text{ hr}$

Every schema functor defines a *dual* transformation on instances

$$\begin{array}{ccc} \mathbf{Inst}(\mathcal{S}) & \xrightarrow{F^*} & \mathbf{Inst}(\mathcal{P}) \\ S(s), S(t) \vdash & \xrightarrow{\quad} & S(t) - S(s) \end{array}$$

Duality is just precomposition:

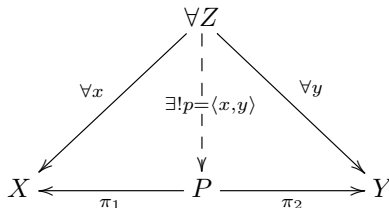
$$\begin{array}{ccc} \mathcal{S} & \xleftarrow{F} & \mathcal{P} \\ S \downarrow & & \downarrow F^*(S) = F.S \\ \mathbf{Sets} & \xlongequal{\quad} & \mathbf{Sets} \end{array}$$

Why not (just) graphs?

- Structured nodes/edges: $J \times M$
- Built-in elements (libraries): $\mathbf{diff} : \mathbb{R}^+ \times \mathbb{R}^+ \longrightarrow \mathbb{R}^+$
- First-class axioms/proofs: $s_{jm} \leq t_{jm} \vdash F(\tau)_{jm} \in \mathbb{R}^+$
- Not a graph homomorphism: $F(\tau) = \ell.p$

Structure in a category

The *Cartesian product* of two objects X and Y is a diagram $X \xleftarrow{\pi_1} P \xrightarrow{\pi_2} Y$ such that, for any object Z and any pair of arrows $x : Z \rightarrow X$ and $y : Z \rightarrow Y$, there exists a unique map $p = \langle x, y \rangle$ such that $p.\pi_1 = x$ and $p.\pi_2 = y$.



Generalized elements

A suggestive notation:

$$x : Z \rightarrow X \rightsquigarrow x \underset{Z}{\in} X$$

Compare:

In set theory	In category theory
$p \in X \times Y$	$p \underset{Z}{\in} X \times Y$
$x \in X, y \in Y, p = \langle x, y \rangle$	$x \underset{Z}{\in} X, y \underset{Z}{\in} Y, \underbrace{p = \langle x, y \rangle}_{p.\pi_1=x, p.\pi_2=y}$

Why generalize? In **Sets**, arrows $\{*\} \rightarrow X$ “see” everything in X , but...

In **Graph**, $\{*\}$ can’t distinguish $\{* \quad *\}$ from $\{* \rightarrow *\}$.

In **Vect**, $\{*\} = \mathbb{R}^0$ can’t see *anything* (zero object).

More structure

In programming, a function $f(x : X) : Y$ is *pure* if

- It has no side effects (e.g., no IO, non-local variable mutation)
- It has consistent return values (e.g., no non-local variable dependence)

The pure fragment of a programming language defines a category **Type**.

The *exponential* adjunction mediates global/generalized elements

$$\begin{array}{c}
 \mathbf{Type} \\
 \begin{array}{c} \uparrow \\ - \times Z \end{array} \left(\begin{array}{c} \downarrow \\ (-)^Z \end{array} \right) \\
 \mathbf{Type}
 \end{array}
 \quad
 \frac{f : X \times Z \longrightarrow Y}{\frac{\frac{\ulcorner f(x, -) \urcorner : X \longrightarrow Y^Z}{\ulcorner f \urcorner : \{*\} \longrightarrow (Y^Z)^X}}{}$$

Round trips: $\text{eval} : Y^Z \times Z \longrightarrow Y$

$\text{coeval} : X \longrightarrow (X \times Z)^Z$

Types in a schema

We can think of schema libraries as

- A subschema $\mathcal{P}_0 \subseteq \mathcal{P}$, together with
- A fixed implementation functor $\mathbf{impl} : \mathcal{P}_0 \rightarrow \mathbf{Type}$

An instance should respect the behavior of the implementation:

$$\begin{array}{ccc} \mathcal{P} & \xrightarrow{P} & \mathbf{Sets} \\ \cup \downarrow & & \uparrow \mathbf{glob} = \mathbf{Hom}(\{*\}, -) \\ \mathcal{P}_0 & \xrightarrow{\mathbf{impl}} & \mathbf{Type} \end{array}$$

Problem: We want $\tau \in \mathbb{R}^+$, but $s, t \in \mathbb{R}^+ \not\Rightarrow t - s \in \mathbb{R}^+$.

Logic in a schema

In general, formulas define subobjects, and inferences define sub-sub-objects:

$$\frac{\varphi(x) \vdash \psi(x)}{\frac{\llbracket \varphi \rrbracket \rhd \text{---} \rhd \llbracket \psi \rrbracket}{X}}$$

Interpretations are defined recursively:

$x = y$	$\varphi \wedge \psi$	$\varphi \vee \psi$	$\exists y.\varphi$
Diagonal	Pullback	Pushout	Image
$\begin{array}{c} X \\ \langle \text{id}, \text{id} \rangle \downarrow \\ X \times X \end{array}$	$\begin{array}{ccc} \llbracket \varphi \wedge \psi \rrbracket & \twoheadrightarrow & \llbracket \psi \rrbracket \\ \downarrow & \lrcorner & \downarrow \\ \llbracket \varphi \rrbracket & \longrightarrow & X \end{array}$	$\begin{array}{ccc} \llbracket \varphi \wedge \psi \rrbracket & \twoheadrightarrow & \llbracket \psi \rrbracket \\ \downarrow & \lrcorner & \downarrow \\ \llbracket \varphi \rrbracket & \longrightarrow & \llbracket \varphi \vee \psi \rrbracket \end{array}$	$\begin{array}{ccc} \llbracket \varphi \rrbracket & \twoheadrightarrow & \llbracket \exists y.\varphi \rrbracket \\ \downarrow & & \downarrow \\ X \times Y & \longrightarrow & X \end{array}$

Proofs as diagrams

Formulas are (sub)objects, inferences & proofs are arrows:

An axiom:

$$\vdash s_{jm} \leq t_{jm}$$

$$\begin{array}{ccc} & & \llbracket x \leq y \rrbracket \\ & \nearrow \ell & \downarrow \Upsilon \\ J \times M & \xrightarrow{\langle s, t \rangle} & \mathbb{R}^+ \times \mathbb{R}^+ \end{array}$$

An inference:

$$x \leq y \vdash (y - x) \in \mathbb{R}^+$$

$$\begin{array}{ccc} \llbracket x \leq y \rrbracket & \xrightarrow{p} & \mathbb{R}^+ \\ \downarrow \Upsilon & & \downarrow \Upsilon \\ \mathbb{R}^+ \times \mathbb{R}^+ & \xrightarrow{\llbracket y - x \rrbracket} & \mathbb{R} \end{array}$$

The cut rule corresponds to concatenation of diagrams

$$\text{e.g., } \vdash F(\tau)_{jm} \in \mathbb{R}^+$$

Functors between graphs

Functors are more flexible than graph homomorphisms:

Nodes map to nodes, but edges map to *paths*.

$$\begin{array}{ccccc}
 \mathcal{P} & & J \times M & \xrightarrow{\tau} & \mathbb{R}^+ \\
 F \downarrow & & \downarrow & & \downarrow \\
 \mathcal{S} & & J \times M & \xrightarrow{\ell} \bullet \xrightarrow{p} & \mathbb{R}^+
 \end{array}$$

Usually interested in *structure-preserving* functors (instances, too!)

Constructions: $F(J \times M) \cong F(J) \times F(M)$

$$\begin{array}{ccc}
 \text{Types:} & \mathcal{P}_0 & \xrightarrow{F(\mathcal{P}_0) \subseteq \mathcal{S}_0} \mathcal{S}_0 \\
 & \searrow \text{impl} & \swarrow \text{impl} \\
 & \text{Type} &
 \end{array}$$

Solutions as functors

Any solution algorithm a defines a matrix endomorphism

$$\begin{aligned} (\mathbb{R}^+)^{J \times M} &\xrightarrow{a} (\mathbb{R}^+)^{J \times M} \\ (\tau_{jm}) &\longmapsto (s_{jm}) \end{aligned}$$

From this, we can define a functor $A : \mathcal{S} \rightarrow \mathcal{P}$

$$A(s)_{jm} = \mathbf{eval}(a(\ulcorner \tau \urcorner), (j, m))$$

$$A(t)_{jm} = A(s)_{jm} + \tau_{jm}$$

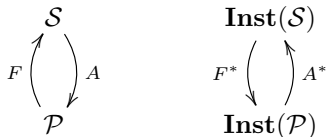
$$J \times M \xrightarrow{\langle \text{id}, \ulcorner \tau \urcorner \rangle} (J \times M) \times (\mathbb{R}^+)^{J \times M} \xrightarrow{\text{id} \times a} (J \times M) \times (\mathbb{R}^+)^{J \times M} \xrightarrow{\mathbf{eval}} \mathbb{R}^+$$

Defining A requires proof: a satisfies the axioms of \mathcal{S} .

Note: Equivalence $(\mathbb{R}^+)^{J \times M} \cong \text{Mat}_{\mathbb{R}^+}(|J|, |M|)$ requires a *labeling*.

A knowledge “graph”

By duality, every problem $P \in \mathbf{Inst}(\mathcal{P})$ defines a solution $A^*(P) \in \mathbf{Inst}(\mathcal{S})$.



The functors should satisfy $F.A = \text{id}_{\mathcal{P}}$ ($\Rightarrow A^*.F^* = \text{id}_{\mathbf{Inst}(\mathcal{P})}$):

$$\begin{aligned} A(F(\tau)) &= A(t - s) \\ &= A(t) - A(s) \\ &= A(s) + \tau - A(s) \\ &= \tau \end{aligned}$$

Variation I

What's the difference?

$$\mathcal{P}' := \left\langle \begin{array}{ccc} & T & \xrightarrow{\tau'} \mathbb{R}^+ \\ j \swarrow & \searrow m & \\ J & & M \end{array} \right\rangle \quad \mathcal{S}' := \left\langle \begin{array}{ccc} & T & \xRightarrow{s'} \mathbb{R}^+ \\ j \swarrow & \searrow m & \xRightarrow{t'} \\ J & & M \end{array} \right\rangle$$

What's the same?

Problem generalization, functorially:

$$\begin{array}{ccc} \mathcal{S}' & \xrightarrow{\exists! \overline{K}} & \mathcal{S} \\ \uparrow F' & & \uparrow F \\ \mathcal{P}' & \xrightarrow{K: T \mapsto J \times M} & \mathcal{P} \end{array}$$

The other direction(s)?

Variation II

Duplicate machines (C = “capability”, a = “assignment”)

$$\mathcal{P}^d := \left\langle \begin{array}{ccc} J \times C & \xrightarrow{\tau^c} & \mathbb{R}^+ \\ M & \xrightarrow[c]{} & C \end{array} \right\rangle \quad \mathcal{S}^d := \left\langle \begin{array}{ccc} M & \xleftarrow{a} & J \times C \\ c \downarrow & & \nearrow p_2 \\ C & & \end{array} \begin{array}{ccc} & & \mathbb{R}^+ \\ & \xrightarrow[s^c]{} & \\ & \xleftarrow[t^c]{} & \end{array} \right\rangle$$

The arrow (bundle, dep. type) $M \rightarrow C$ represents a family of sets $\{M_c\}_{c \in C}$.

This time, we can go both ways (sort of)

$$\begin{array}{ccccc} \mathcal{S}^d & \xrightarrow{\exists! \bar{I}: a \mapsto p_2} & \mathcal{S} & \xrightarrow{H: s, t \mapsto s|_a, t|_a} & \mathcal{S}^d \\ \uparrow F^d & & \uparrow F & \times & \uparrow F^d \\ \mathcal{P}^d & \xrightarrow{I: c \mapsto \text{id}_M} & \mathcal{P} & \xrightarrow{G: M \mapsto C} & \mathcal{P}^d \end{array}$$

Here $H : M \mapsto M$ and $s|_a, t|_a$ denote extension by zero along a .

Variation III

Duplicate jobs (\mathcal{P} =Process *catalog*, \mathcal{O} =Orders database)

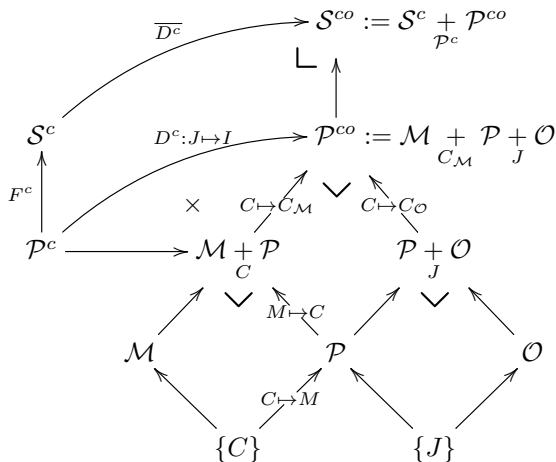
$$\mathcal{O} := \left\langle \begin{array}{ccccc} & C & \xleftarrow{c} & O & \xleftarrow{o} & I \\ & \downarrow b & & \swarrow d & & \downarrow j \\ \mathbb{R}^+ & & & & & J \\ & & & \xleftarrow{k} & & \end{array} \right\rangle, \quad b = r + \sum_{o:O_c} \sum_{i:I_o} k(j(i))$$

Extract the daily schedule by mapping to a pushout:

$$\begin{array}{ccc} \mathcal{P} & \xrightarrow{\quad} & \mathcal{O} \underset{J}{+} \mathcal{P} \\ \\ J \times M \vdash & \xrightarrow{\quad} & I \times M \\ \downarrow \tau & & \downarrow j \times \text{id} \\ & & J \times M \\ & & \downarrow \tau \\ \mathbb{R}^+ \vdash & \xrightarrow{\quad} & \mathbb{R}^+ \end{array}$$

Variation IV

Duplicate jobs and machines (\mathcal{M} =Shop floor model)



Wrapping Up

Recap:

- Bite-sized semantic models & functorial instances
- Built-in logic & computation via (preservation of) structure
- Knowledge graphs as schemas & functors.

More goodies:

- Build-your-own semantics (presheaves)
- Internal concepts generate external schemas (Yoneda/slice cat.)
- Relationships between relationships (Natural transformations)

The bad news...

- Limited tooling
- Steep learning curve

Thank you!

PS. This talk is based on a paper under review, but a draft is available on request from `spencer.breiner@nist.gov`.